

ArTeC® Robo 2.0

機器車



禁止未經授權的複制和分發

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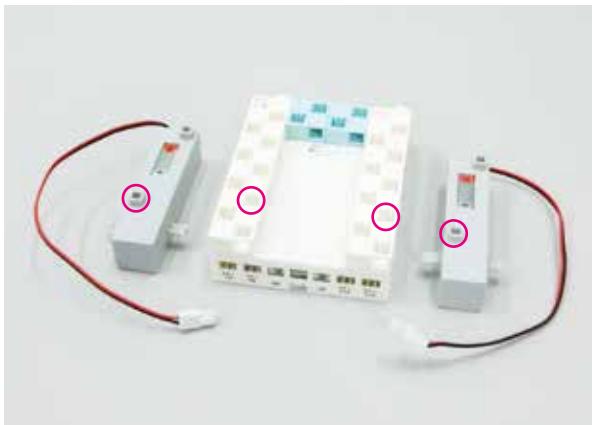
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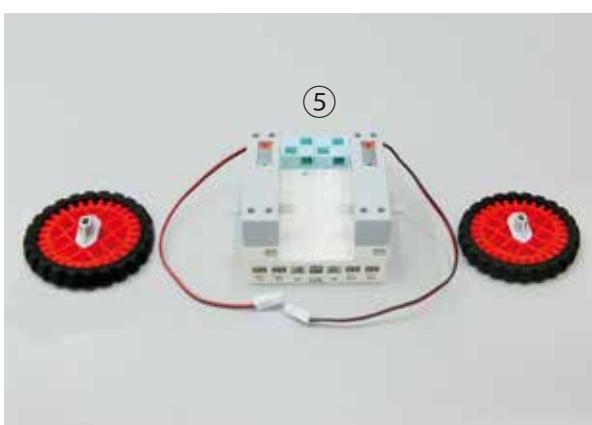
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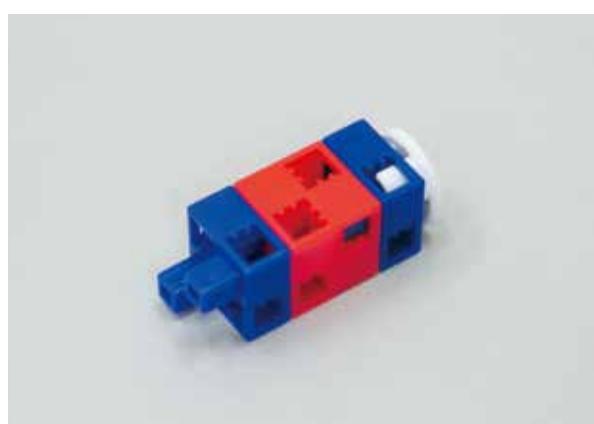
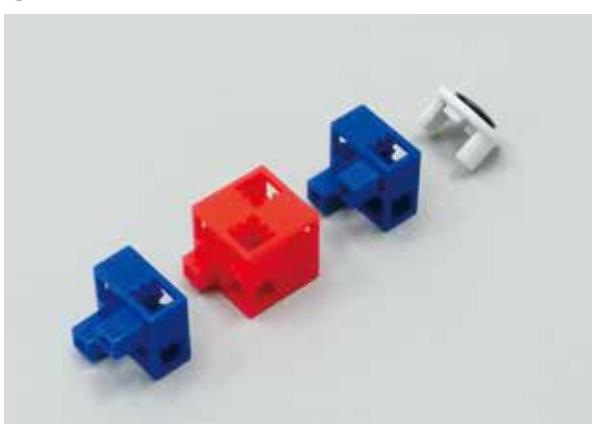
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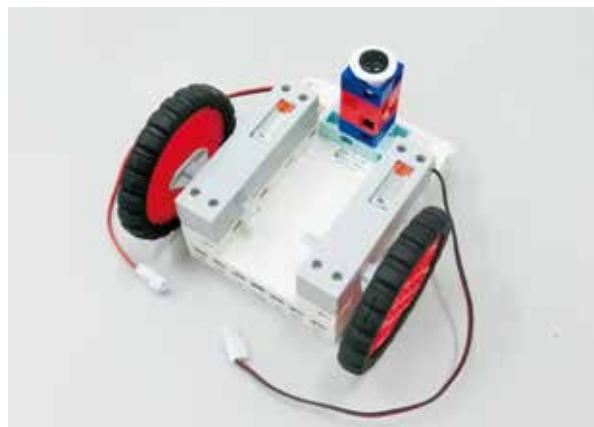
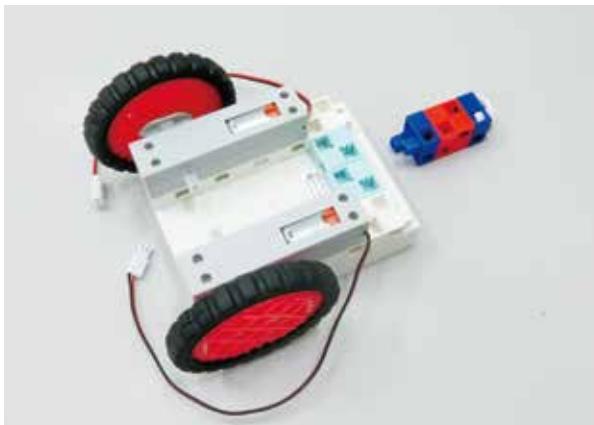
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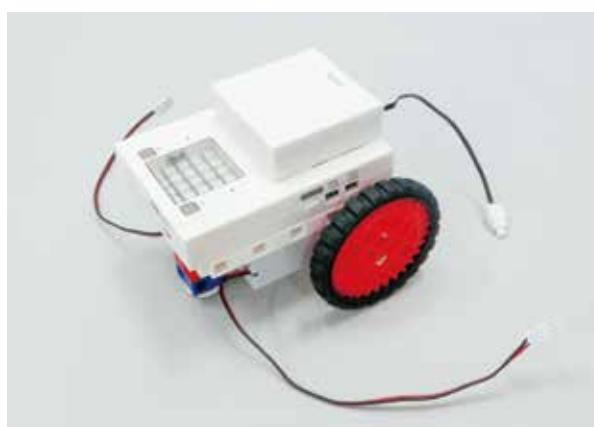
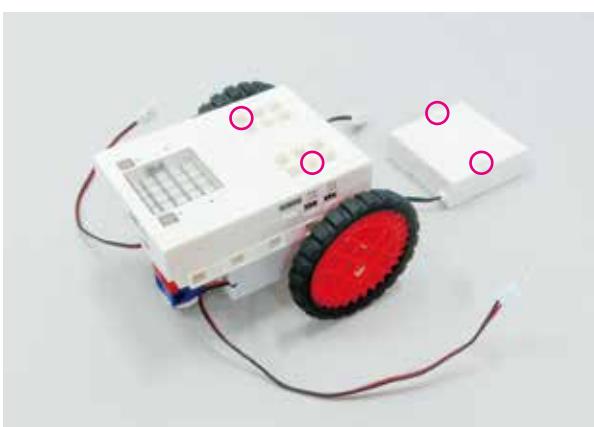
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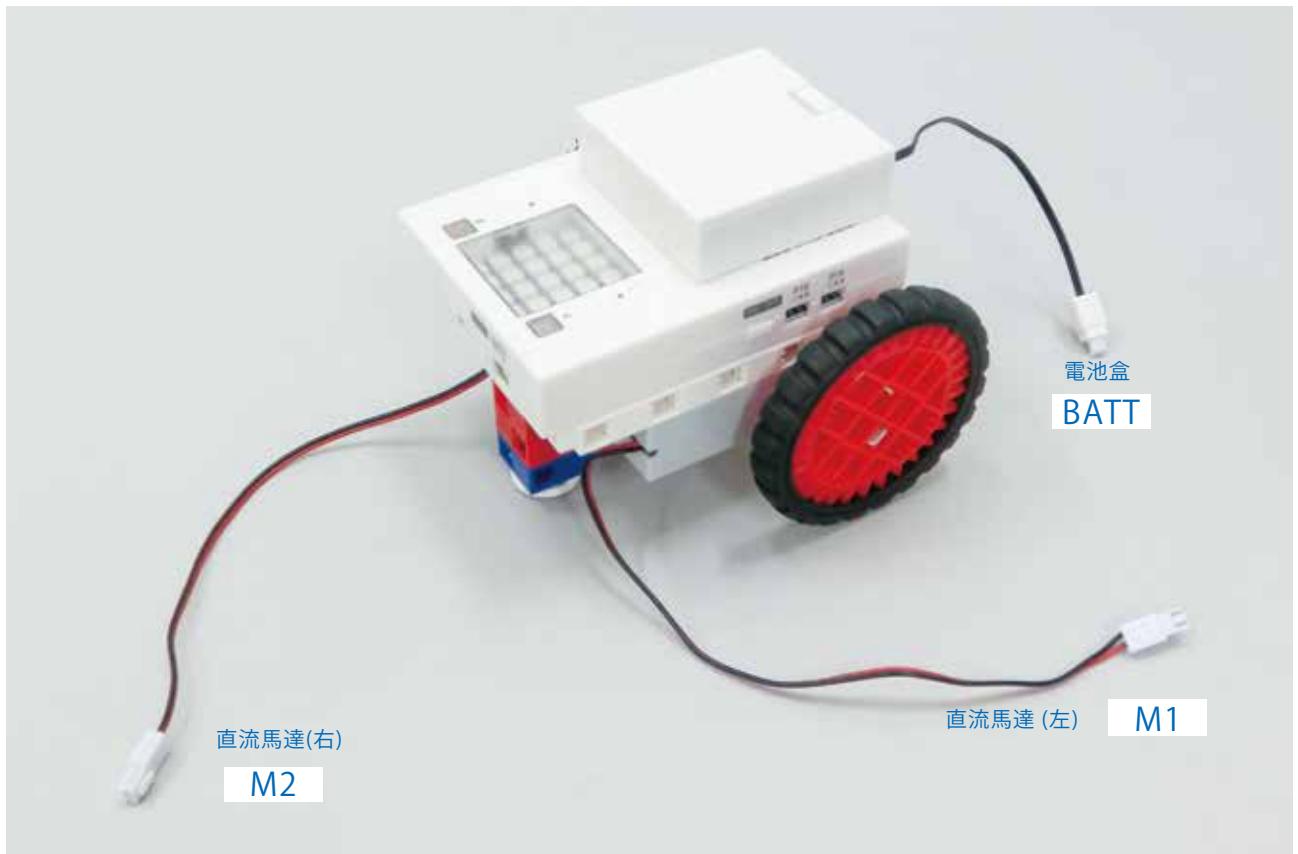


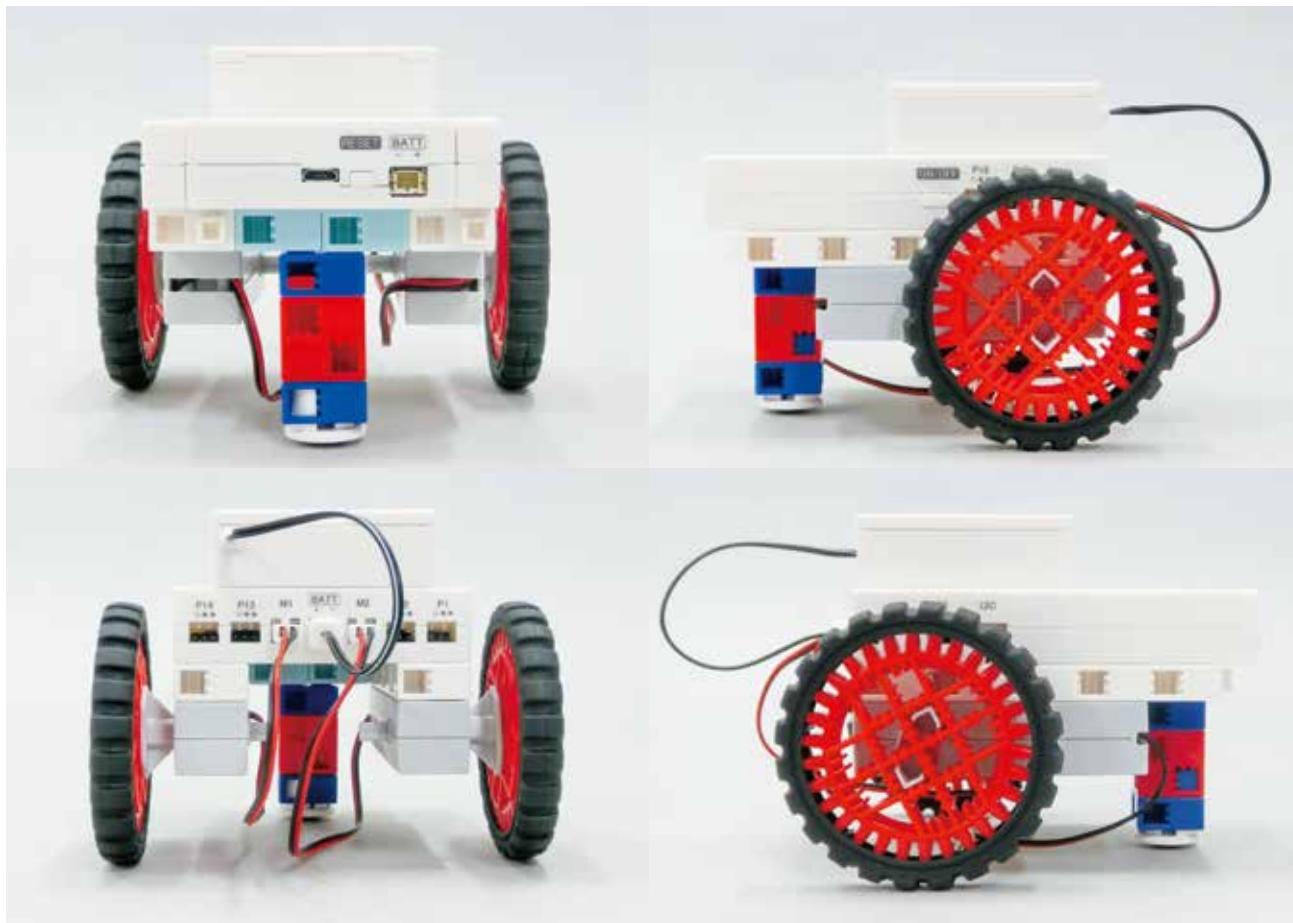
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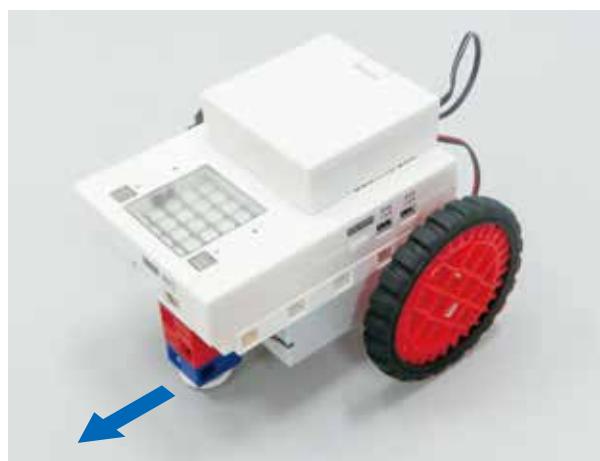
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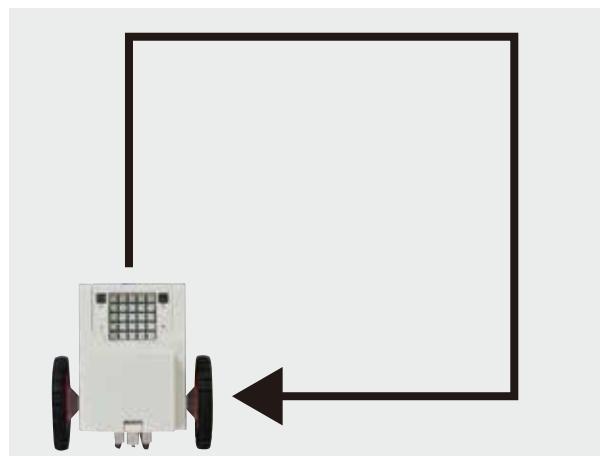


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加載並傳輸示例程序 [RobotCar_1](#),
您的機器人車將能夠在正方形中行駛!

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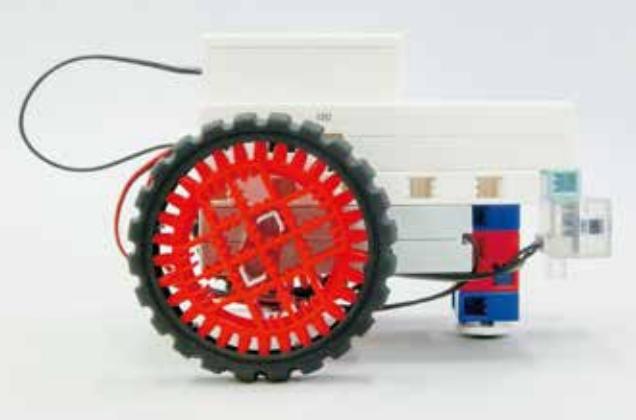
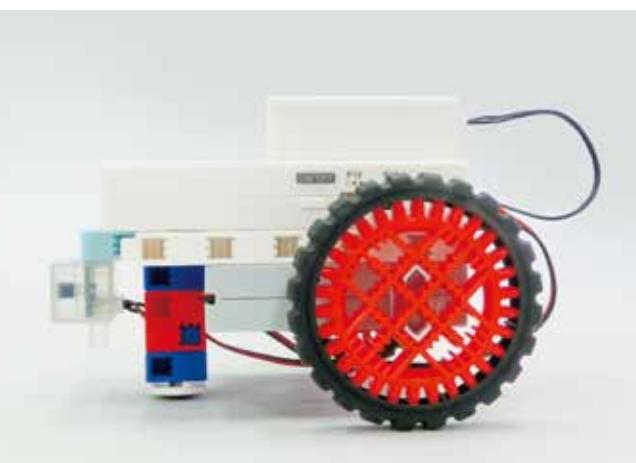
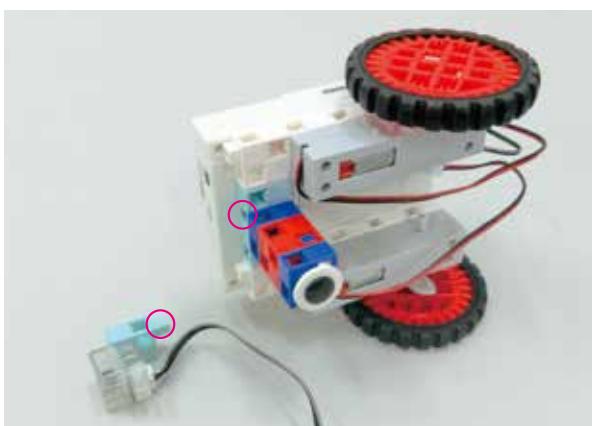


(前→右→前→右→前→右→前→右)

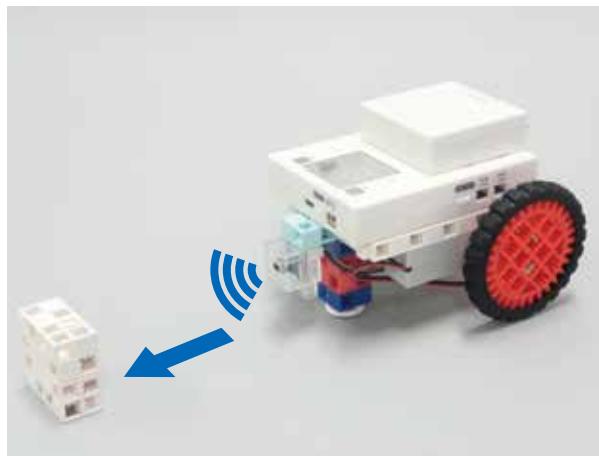
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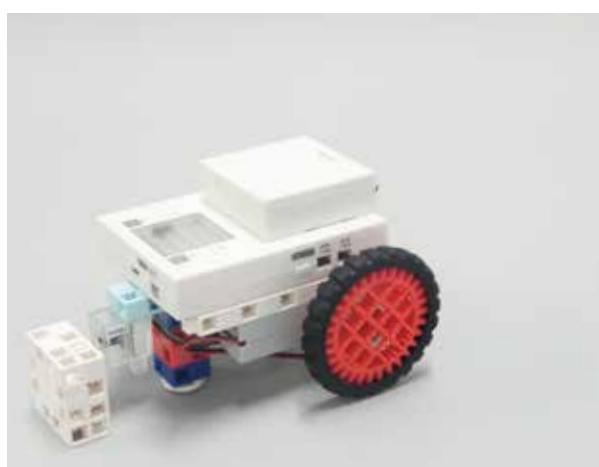
加載示例程序 [RobotCar_2](#),

您的機器人汽車將像防撞車一樣運行！

汽車的感應器將在行駛時檢測到

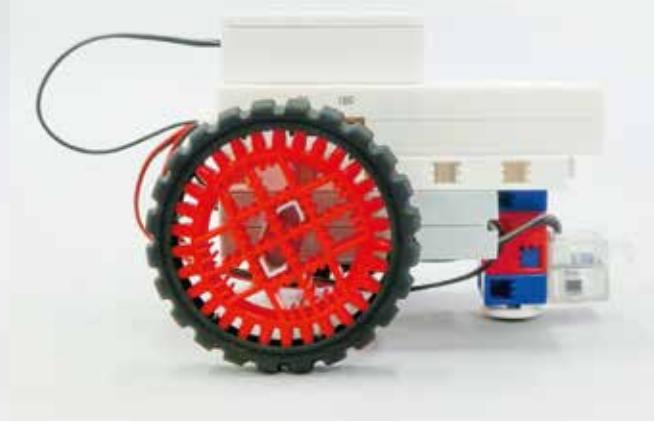
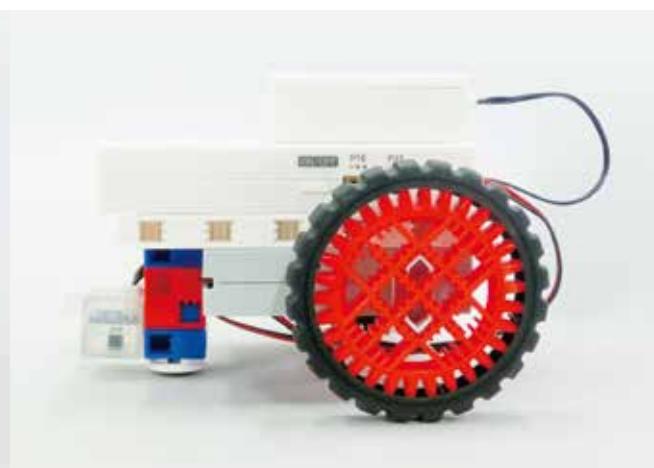
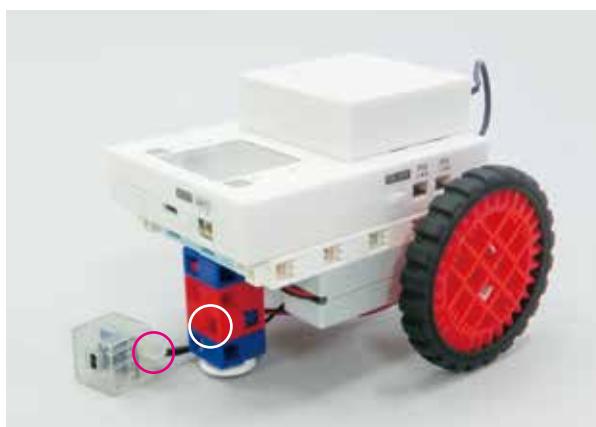
前方的障礙物，並在撞到它們之前自動停止。

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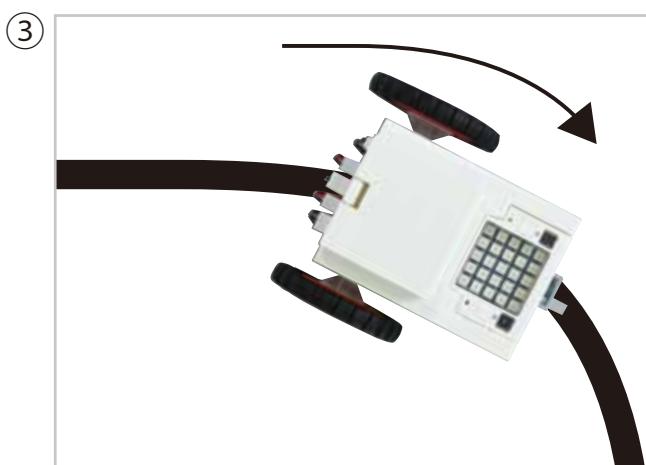
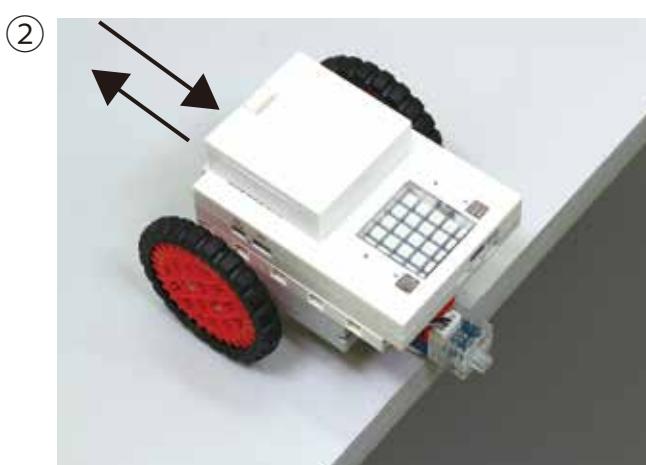


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加載示例程序 RobotCar_3,
您的機器人車將像防摔車一樣運作！
感應器可以檢測到它行駛時前方會否跌落，
它會後退以防止跌落。
(您需要在白色表面上運行汽車才能運作！)



加載示例程序 RobotCar_4,
您將擁有一輛尋線機器人汽車！
汽車的感應器可以區分黑色和白色，
並利用這些信息沿著黑線行駛。

下一頁有一個跟蹤線圖像，您可以打印出來並使用。
(打印前將圖像放大到 A3 尺寸。)

